

Leveraging Fuzzy System to Reduce Uncertainty of Decision Making in Software Engineering Automation

Yueke Zhang

Southwest University

Yu Huang

Vanderbilt University



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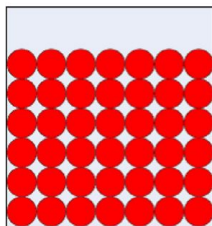


Ideal Data vs. Real Life Data

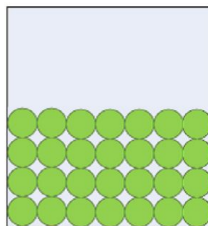
Ambiguity

Partial information

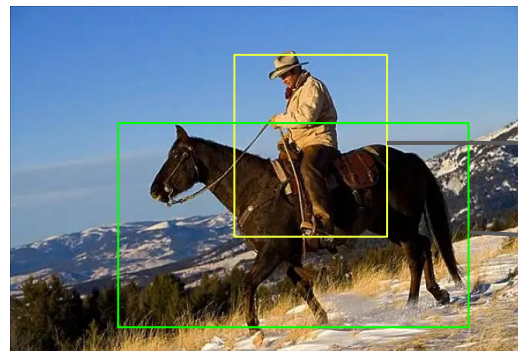
ideal



$P1=0.6$



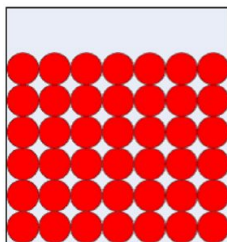
$P2=0.4$



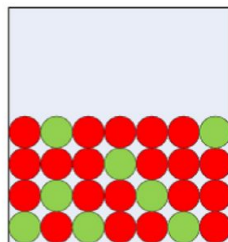
human 100%

horse 100%

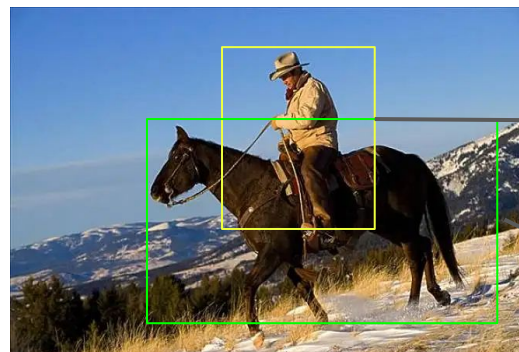
real



$P1=0.6$



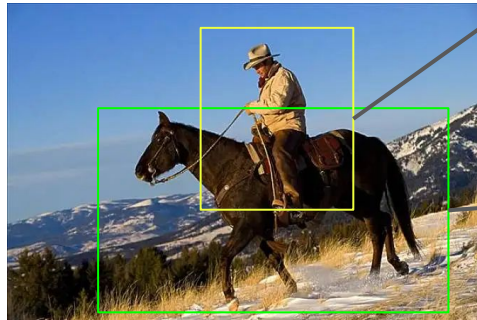
$P2=0.4$



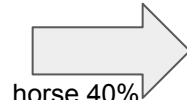
human 60%
monkey 20%
unknown 20%

horse 40%
mule 40%
unknown 20%

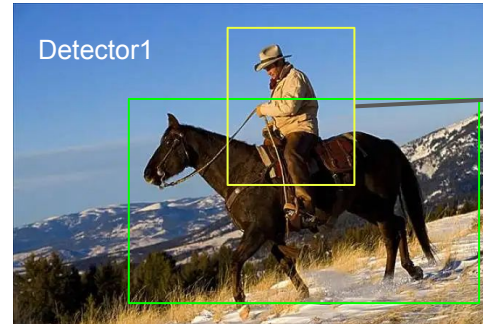
Evidence theory



human 60%
monkey 20%
unknown 20%



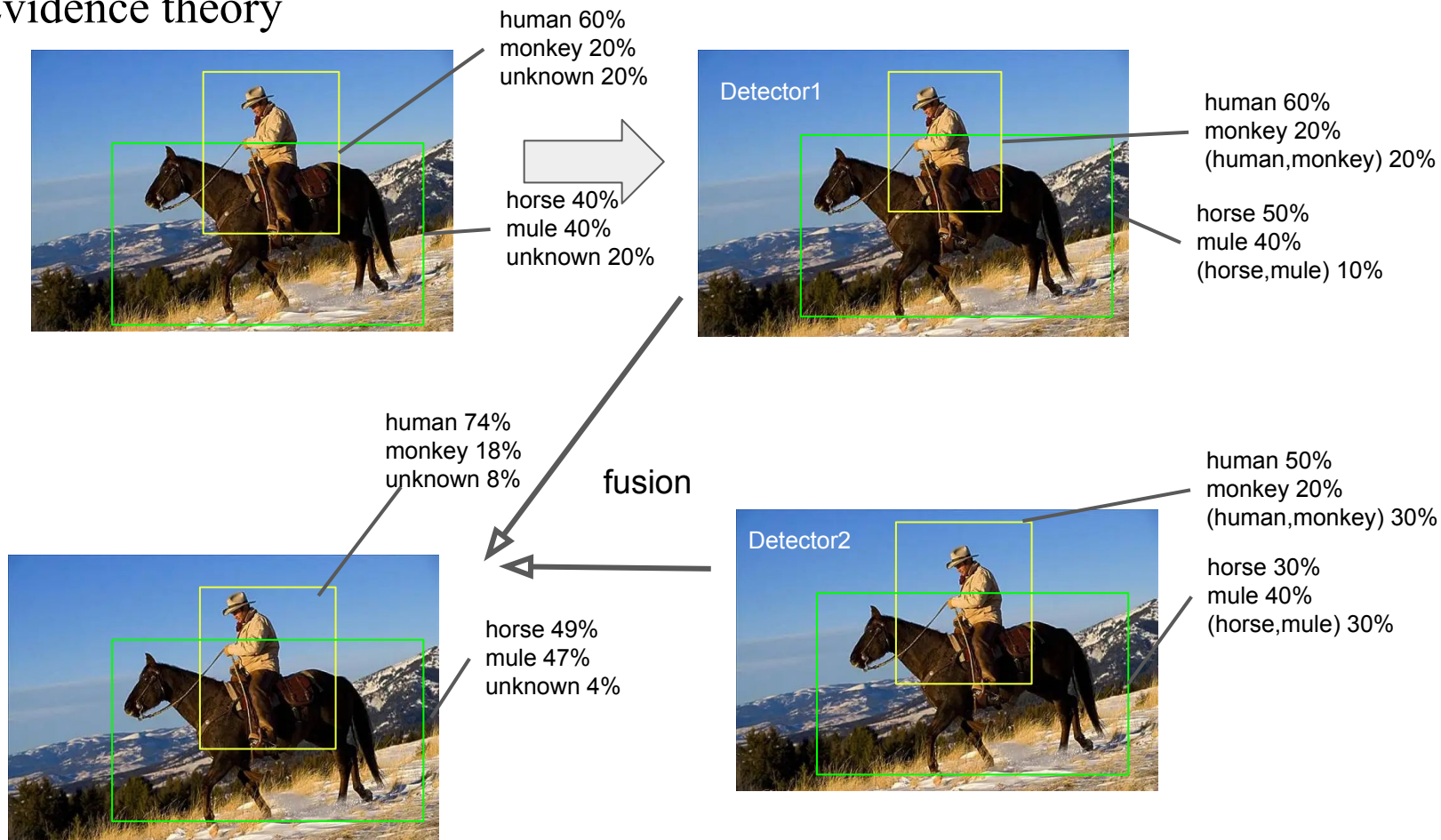
horse 40%
mule 40%
unknown 20%



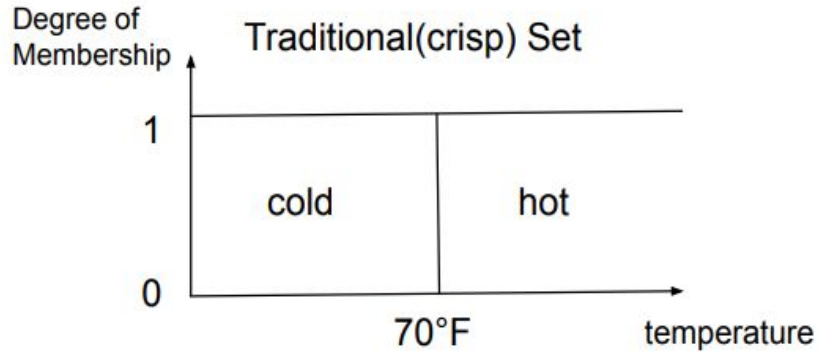
human 60%
monkey 20%
(human,monkey) 20%

horse 50%
mule 40%
(horse,mule) 10%

Evidence theory

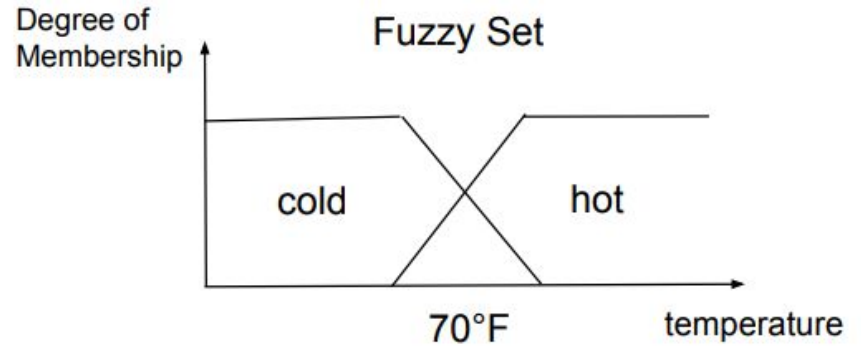


The fuzzy set theory



For 70°F

$m(\text{cold})=1$ or $m(\text{hot})=1$



For 70°F

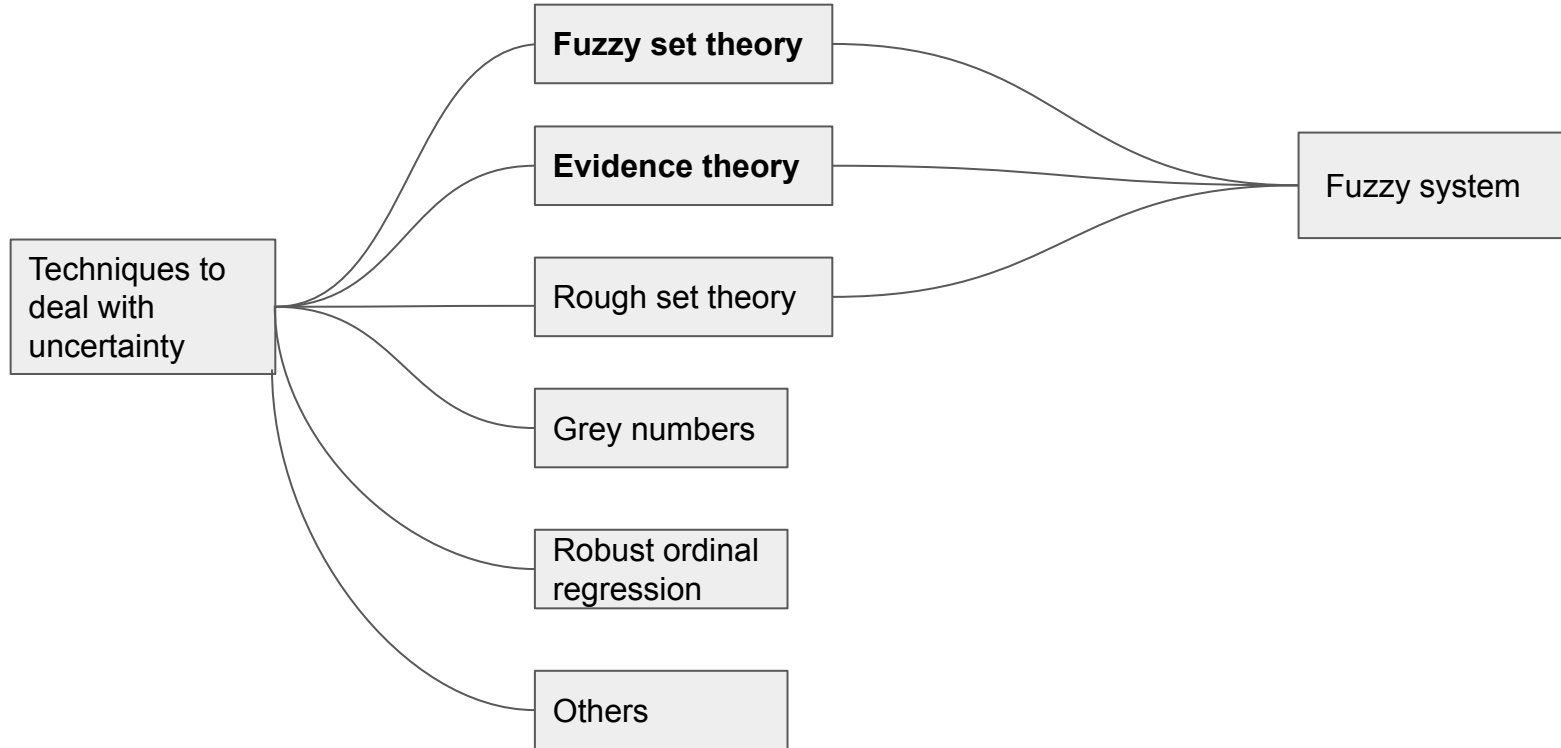
$m(\text{cold})=0.5$ $m(\text{hot})=0.5$

For 60°F

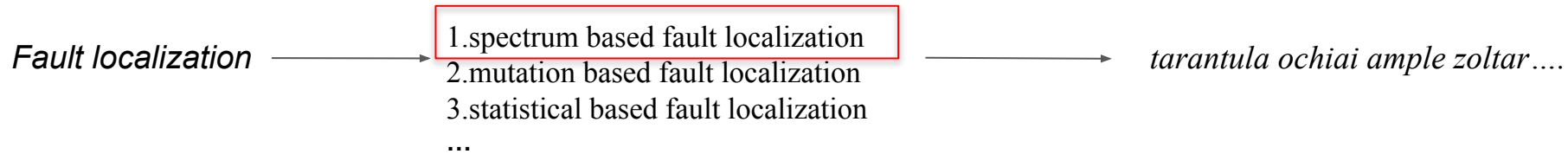
$m(\text{cold})=0.4$ $m(\text{hot})=0.6$

$m(a)$ means membership of a

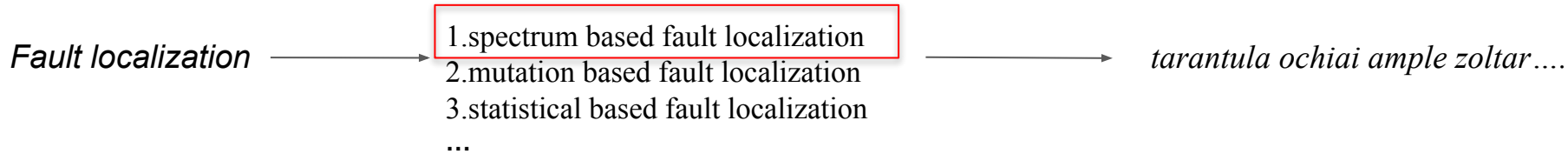
What is fuzzy based uncertain decision making?



Fault localization and its decision-making process



Fault localization and its decision-making process



$$ochiai(e) = \frac{failed(e)}{totalfailed \times (failed(e)) + passed(e)}$$

$$ample(e) = \left| \frac{failed(e)}{totalfailed - failed(e)} - \frac{passed(e)}{totalpassed - passed(e)} \right|$$

$$tarantula(e) = \frac{failed(e) \times totalpassed}{failed(e) \times totalpassed + passed(e) \times totalfailed}$$

*A decision with
three opionions*

Ochiai vs. Ample (Exam score)

	Ochiai	Ample
Math 1	0.004	0.026
Math 14	0.207	0.024
Math 19	0.013	0.016
Math 23	0.105	0.087
Math all	0.117	0.122
defects4j v.1.1.0	0.099	0.104

Different SBFL formulas in FL

$$\text{DM1 } ochiai(e) = \frac{failed(e)}{totalfailed \times (failed(e)) + passed(e)}$$



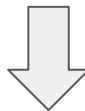
$$\begin{aligned} m(buggy) &= norm(ochiai(e)) \\ m(unknown) &= 1 - m(buggy) \end{aligned}$$

$$\text{DM2: } ample(e) = \left| \frac{failed(e)}{totalfailed - failed(e)} - \frac{passed(e)}{totalpassed - passed(e)} \right|$$



$$\begin{aligned} m(buggy) &= norm(ample(e)) \\ m(unknown) &= 1 - m(buggy) \end{aligned}$$

Combination Rule



Final $m(buggy)$

A fusion example

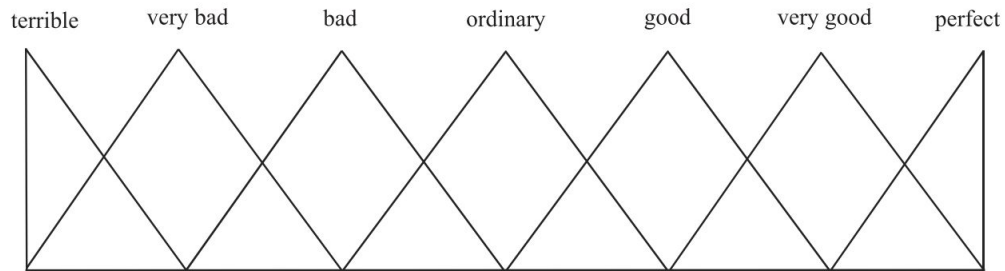
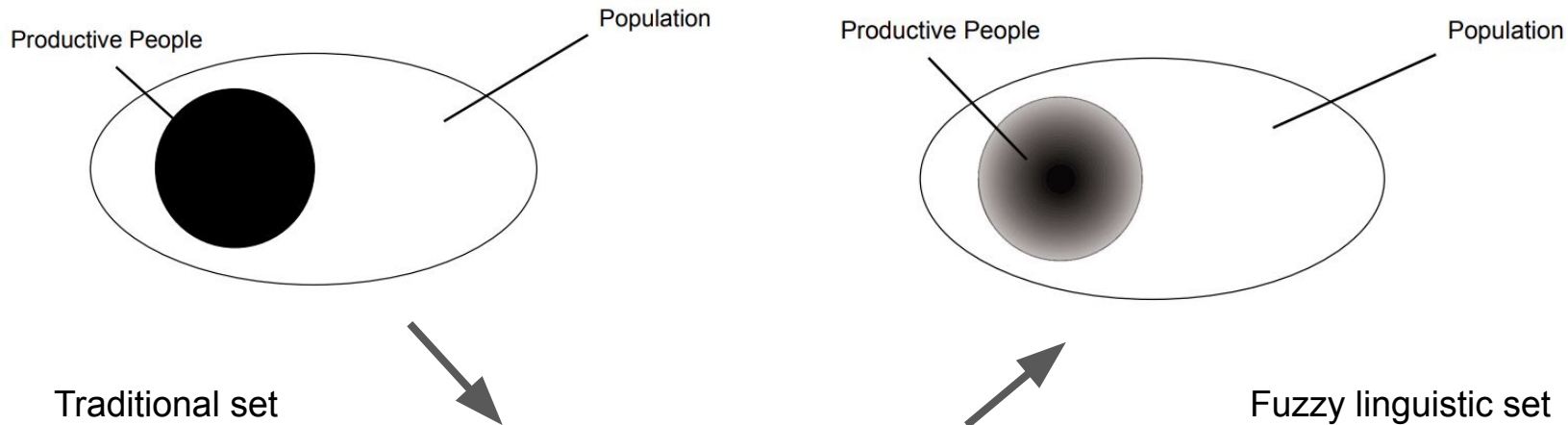
Line #	Line of Code	Ochiai	Ample	Zoltar	Fuzzy
1	<code>currentEvent.stepAccepted(eventT, eventY);</code>	0.75 (113)	0.48 (366)	0.53 (124)	0.94 (124)
2	<code>isLastStep = currentEvent.stop();</code>	0.75 (122)	0.48 (362)	0.53 (114)	0.94 (126)
3	<code>for (final StepHandler handler : stepHandlers) {</code>	0.75 (121)	0.48 (370)	0.53 (121)	0.94 (131)
4	<code>handler.handleStep(interpolator, isLastStep);}</code>	1.00 (13)	0.54 (187)	1.00 (13)	1.00 (6)
5	<code>if (isLastStep) {</code>	0.75 (95)	0.48 (390)	0.53 (95)	0.94 (105)
6	<code>System.arraycopy(eventY, 0, y, 0, y.length);</code>	0 (8283)	0.08 (7518)	0 (8283)	0.08 (7531)
7	<code>for (final EventState remaining : occurringEvents) {</code>	0 (8293)	0.08 (7519)	0 (8293)	0.08 (7529)
8	<code>remaining.stepAccepted(eventT, eventY); }</code>	0 (8269)	0.01 (7750)	0 (8269)	0.01 (7761)
	Exam Score	0.41	0.39	0.41	0.38

Buggyline

Exam Score

Rank in code sinppet

Other insights: importing fuzzy theory in human study



Challenge and Opportunities

- **Modeling**

Measure uncertainty in domain knowledge

- **Computational overhead**

The computational cost of fusion rule is negligible, but we require different information sources.

- **Evaluation**

Golden standard

Expert decision

Summary

We present the method of modeling uncertain decision making in SE

- How does uncertain decision making look like?
- How do we measure uncertainty in real life data?
- How do we model uncertainty in fault localization?
- Insights in other directions in SE



